DS04-13514-1E

## Linear IC Converter

**CMOS** 

# D/A Converter for Digital Tuning

## MB40D001

#### DESCRIPTION

The MB40D001 is an 8-bit D/A converter with 12 built-in channels. The 12 sets of analog outputs have built-in OP amps to enable use with large current drive applications.

CS (chip select) data input/output format is used to enable connection to a serial bus. A built-in 12-bit I/O expander provides serial <=> parallel conversion (8 of the 12 bits are also used with analog output).

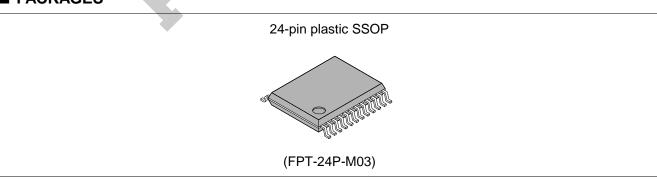
The MB40D001 can be adapted for microcontroller port expansion, or replacement of electronic volume control or semi-fixed calibration resistance.

Also, the MB40D001 is function- and pin-compatible with the MB88146A, for easy replacement when reducing sysytem operating voltage.

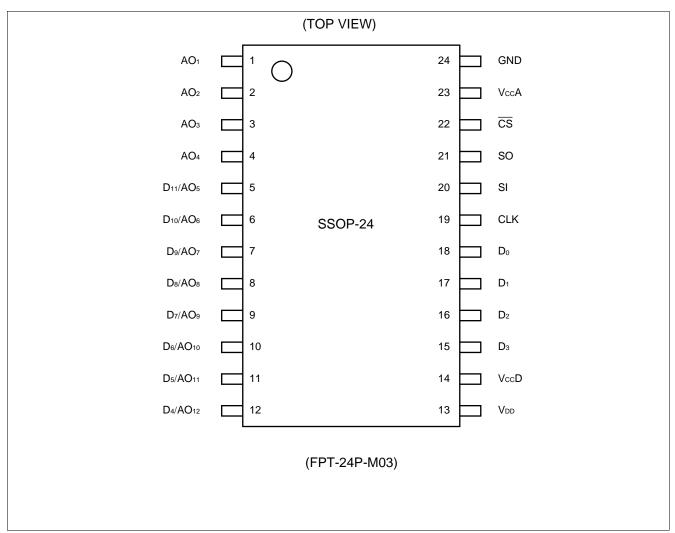
#### **■ FEATURES**

- Supply voltage 2.7V to 3.6V (Power consumption 0.7mW/ch typ.)
- Compact package: SSOP-24
- R-2R type 8-bit D/A converter with 12 built-in channels
- Built-in 12-bit I/O expander (8 of 12 bits also used with analog output)
- Built-in analog amplifier (sink current max. 0.4mA, source current max. 1.0mA)
- Built-in power-on detector circuit (detects VccD power-on, and performs initialization)
- Separate MCU interface power supply (VccD), OP amp supply (VccA), D/A converter supply VDD
- Analog output range 0V to VccA.
- Serial data input/output operation to maximum of 2.5MHz (1.5MHz in cascade operation)
- CMOS process

#### ■ PACKAGES



#### **■ PIN ASSIGNMENT**

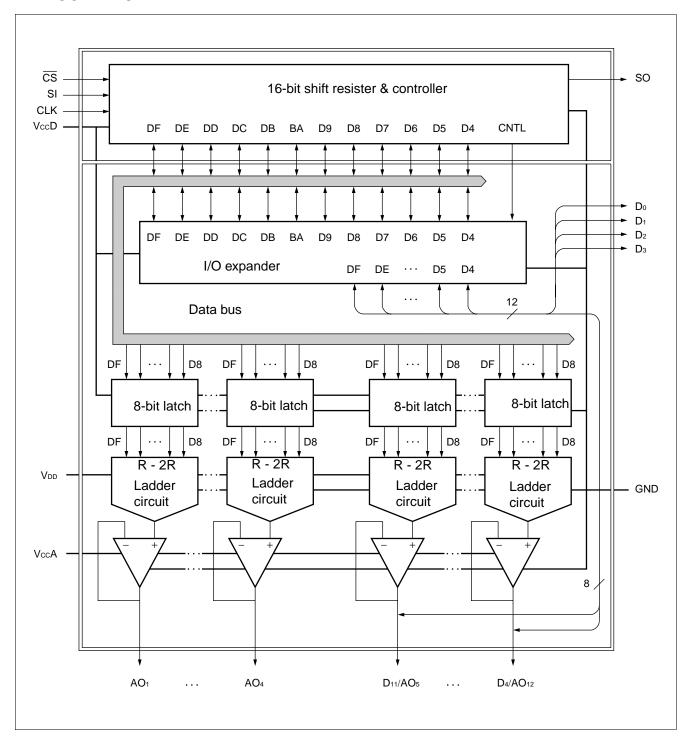


#### **■ PIN DESCRIPTION**

Pin no.	Symbol	Description
1 to 4	AO <sub>1</sub> to AO <sub>4</sub>	D/A converter analog output pins (VDD-GND output). (Default state: #00 setting level output)
5 to 12	D <sub>11</sub> /AO <sub>5</sub> to D <sub>4</sub> /AO <sub>12</sub>	I/O expander parallel I/O pins (VccA/GND output 0.5 VccA/0.2 VccA input), also used as D/A converter analog output pins (VDD - GND output). Pin state is controlled by input data. See "Data Configuration". (Default state: Input mode, high-impedance state.)
13	V <sub>DD</sub> *1	D/A converter reference power supply pin.
14	VccD*1	MCU interface power supply (Power supply for I/O expander).
15 to 18	D <sub>3</sub> toD <sub>0</sub>	I/O expander parallel I/O pins (VccD/GND output 0.5 VccD/0.2VccD input). Pin state is controlled by input data. See "Data Configuration". (Default state: Input mode, high-impedance state.)
19	CLK*2	Shift clock input pin. When $\overline{CS}$ = "L", SI data is loaded into the shift register at the rise of the shift clock signal.
20	SI*2	Data input pin (serial input pin). Used for 16-bit serial data input.
21	SO	Data output pin (serial output pin). First-bit (LSB) data from the 16-bit shift register is output in synchronization with the fall of the shift clock signal. When CS = "H", this pin is in high impedance state.
22	<del>CS</del> *₂	Chip select signal input pin. Input to shift registers is enabled when the $\overline{\text{CS}}$ signal falling edges. Shift register contents can be executed when the $\overline{\text{CS}}$ signal rising edges.
23	VccA*1	Analog unit power supply pin (Power supply for the OP amp.).
24	GND	Common GND pin.

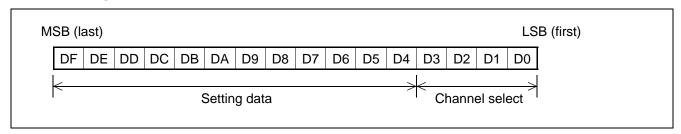
<sup>\*1:</sup> Be sure that  $V_{CC}A \ge V_{CC}D$ , and that  $V_{CC}A \ge V_{DD}$ . \*2: Do not leave this pin in floating state.

#### **■ BLOCK DIAGRAM**



#### **■ DATA CONFIGURATION**

### 1. Data Configuration



#### 2. Channel Select

D3	D2	D1	D0	Function
0	0	0	0	Don't Care/special function
0	0	0	1	AO <sub>1</sub> selected
0	0	1	0	AO <sub>2</sub> selected
to	to	to	to	to
1	0	1	1	AO <sub>11</sub> selected
1	1	0	0	AO <sub>12</sub> selected
1	1	0	1	I/O expander (serial → parallel)
1	1	1	0	I/O expander (parallel → serial)
1	1	1	1	Expander status register (ESR)

#### 3. Setting Data

• Don't Care/special function (Channel select = "0000")

DF	DE	DD	DC	DB	DA	D9	D8	D7	D6	D5	D4	Analog output voltage level
×	×	×	×	×	×	×	×	0	0	0	0	Don't Care
to	Don't Care											
×	×	×	×	×	×	×	×	1	0	1	1	Don't Care
0	0	0	0	0	0	0	0	1	1	0	0	GND (all channels)
0	0	0	0	0	0	0	1	1	1	0	0	V <sub>DD</sub> /256 × 1 (all channels)
0	0	0	0	0	0	1	0	1	1	0	0	V <sub>DD</sub> /256 × 2 (all channels)
to												
1	1	1	1	1	1	1	0	1	1	0	0	V <sub>DD</sub> /256 × 254 (all channels)
1	1	1	1	1	1	1	1	1	1	0	0	V <sub>DD</sub> /256 × 255 (all channels)
×	×	×	×	×	×	×	×	1	1	0	1	High impedance (I/O expander state)*
×	×	X	×	×	×	×	×	1	1	1	0	Reset (state when power is ON)
×	×	×	×	×	×	×	×	1	1	1	1	Don't Care

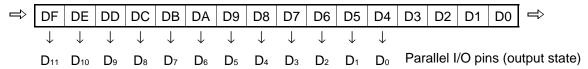
- x: Don't care \*: Hi-Z output on all channels of AO₅ through AO₁₂
  - D/A Converter (Channel select = "0001" to "1100")

DF	DE	DD	DC	DB	DA	D9	D8	D7	D6	D5	D4	Analog output voltage level
0	0	0	0	0	0	0	0	0	0	0	0	GND
0	0	0	0	0	0	0	1	0	0	0	0	V <sub>DD</sub> /256 × 1
0	0	0	0	0	0	1	0	0	0	0	0	V <sub>DD</sub> /256 × 2
0	0	0	0	0	0	1	1	0	0	0	0	V <sub>DD</sub> /256 × 3
to												
1	1	1	1	1	1	0	1	0	0	0	0	V <sub>DD</sub> /256 × 253
1	1	1	1	1	1	1	0	0	0	0	0	V <sub>DD</sub> /256 × 254
1	1	1	1	1	1	1	1	0	0	0	0	V <sub>DD</sub> /256 × 255
×	×	×	×	×	×	×	×	0	0	0	1	High impedance (I/O expander state)*
×	×	×	×	×	×	×	×	0	0	1	0	Don't Care
to	Don't Care											
×	×	×	×	×	×	×	×	1	1	1	1	Don't Care

×: Don't care \*: Only AO₅ through AO₁₂ output is valid

I/O Expander [Channel select = "1101"]: Serial → Parallel Conversion
 Performs parallel conversion of data bits D4 to DF for output on pins D₀ to D₁₁.
 Note that only those pins designated for output in the ESR (expander status register) are output.

#### Shift register



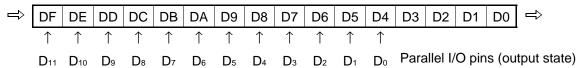
I/O Expander [Channel select = "1110"]: Parallel → Serial Conversion

Writes data from D<sub>0</sub> to D<sub>11</sub> pins to bits D4 to DF in the shift register.

Data is output to the SO pin on the shift clock (CLK) signal (The first 4 bits output data D0 to D3, so the converted output should be read as data bits 5 through 16.).

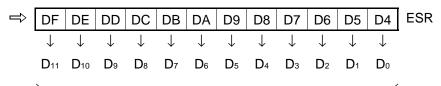
Note that the data value is "0" for pins designated for output in the ESR (expander status register) as well as analog output pins.

#### Shift register



• Expander Status Register [Channel select = "1111"]

#### Shift register



This register sets the status of each pin.

Setting	Pin status
"0"	<ul> <li>Input standby status (Hi-Z output)</li> <li>D<sub>11</sub> to D<sub>4</sub> pins used for analog output should be set to "0".</li> </ul>
"1"	Output state

Note: After power VccD is turned ON (or after a reset), the state of pins and registers is as follows.

Pin	State
AO <sub>1</sub> to AO <sub>4</sub>	"L" output
D <sub>11</sub> /AO <sub>5</sub> to D <sub>4</sub> /AO <sub>12</sub>	Hi-Z state (input state)
D <sub>3</sub> to D <sub>0</sub>	Hi-Z state (input state)

Register	State
Shift register	Bits DF to D8 are "0," and D7 to D0 are not defined (retain prior state).
D/A register	All reset to "0".
Parallel output register	Not defined (retain prior state).
Expander status register (ESR)	All reset to "0".

- ESR settings have priority in determining pin states. Switching between input standby state and analog output state is enabled even when the ESR value is "1". When the ESR value returns to "0", the pin returns to its previously defined state.
  - In input standby state with AO set for Hi-Z output, the AO output setting can be used for transition to AO output state.

#### ■ ABSOLUTE MAXIMUM RATINGS

Doromotor	Cumbal	Conditions	Ra	Unit		
Parameter	Symbol	Conditions	Min.	Max.	Offic	
	VccA		-0.3	+7.0	V	
Power supply voltage	VccD	Based on GND (Ta = +25°C)	-0.3	+7.0	V	
	V <sub>DD</sub>	(14 125 5)	-0.3	VccA*	V	
Input voltage 1	Vin1	SI, CLK, <del>CS</del> ,	-0.3	VccD + 0.3	V	
Output voltage 1	Vout1	SO, Do to D3	-0.3	VccD + 0.3	V	
Input voltage 2	Vin2	D <sub>4</sub> to D <sub>11</sub>	-0.3	VccA + 0.3	V	
Output voltage 2	V <sub>out</sub> 2	D4 10 D11	-0.3	VccA + 0.3	V	
Power consumption	P <sub>D</sub>	_	_	250	mW	
Operating temperature	Та	_	-20	+85	°C	
Storage temperature	T <sub>stg</sub>	_	<b>-</b> 55	+150	°C	

<sup>\*:</sup>  $V_{CC}A \ge V_{DD}$ 

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

#### ■ RECOMMENDED OPERATING CONDITIONS

Davamatar	Cumbal	Conditions		Unit		
Parameter	Symbol	Conditions	Min.	Тур.	Тур. Мах.	
	VccA	_	2.7	3.0	3.6	V
Davis a supeli contra a s	VccD	_	2.7	_	3.6	V
Power supply voltage	V <sub>DD</sub>	$V_{CC}A \geqq V_{DD}$	2.0	_	VccA	V
	GND	_	_	0	_	V
A mala manutan utan utan	IAL	Source current	_	_	1.0	mA
Analog output current	Іан	Sink current	_	_	0.4	mA
Oscillation limit output capacity	CoL	_	_	_	1.0	μF
Operation temperature	Та	_	-20	_	+85	°C

Note: Data in registers is retained in standby mode (digital supply: VccD voltage, analog supply: GND).

**WARNING:** The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.

#### **■ ELECTRICAL CHARACTERISTIC**

#### 1. DC Characteristics

#### (1) Digital section

Doromotor	Cymhal	Din nama	Conditions		Value		Unit	
Parameter	Symbol	Pin name	Conditions	Min.	Тур.	Max.	Uiiit	
Power supply voltage	VccD		_	2.7	3.0	3.6	V	
Power supply current	IccD	VccD	CLK =1 MHz, (Unloaded)		0.1	0.35	mA	
Standby current	IccS	V 0.02	CLK, SI, CS Stop Vin = VccD or GND	-10	_	+10	μА	
Input leak current	IILK1	CLK, SI,	Vin = 0 to VccD	-10	_	+10	μΑ	
"H" level input voltage	V <sub>IH1</sub>	CS,	_	$0.5 \times VccD$	_	_	V	
"L" level input voltage	V <sub>IL1</sub>	D₀ to D₃	_	_	_	0.2 × VccD	V	
Output high-impedance leakage current	lolk	SO	Vin = 0 to VccD	-10	_	+10	μΑ	
"H" level output voltage	V <sub>OH1</sub>	SO,	Iон = -0.4 mA	VccD-0.4	_	_	V	
"L" level output voltage	V <sub>OL1</sub>	D <sub>0</sub> to D <sub>3</sub>	IoL = 2.5 mA	_	_	0.4	V	

#### (2) D/A converter section

Parameter	Symbol	Pin name	Conditions		Unit		
Parameter	Syllibol	riii iiaiiie	Conditions	Min.	Тур.	Max.	Offic
Power supply voltage	V <sub>DD</sub>	$V_{DD}$	$V_{DD} \leqq V_{CC}A$	2.0	3.0	3.6	V
Power supply current	IDD		$V_{DD} \leqq V_{CC}A$	_	0.7	1.9	mA
Resolution	Res			_	8	_	bit
Monotonic increase	Rem	AO to AO	Liniondad	_	8	_	bit
Nonlinearity error	LE	AO <sub>1</sub> to AO <sub>12</sub>	Unioaded	-1.5	_	+1.5	LSB
Differential linearity error	DLE			-1.0	_	+1.0	LSB

Nonlinearity error: Deviation (error) in input/output

curves with respect to an ideal straight line connecting output voltage at "05" and output voltage

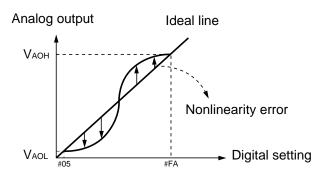
at "FA".

Differential linearity error:

Deviation (error) in amplification with respect to theoretical increase in

amplification per 1-bit increase in

digital value.



Note:The value of VAOH and VDD, and the value of VAOL and GND are not necessarily equivalent.

#### (3) Operational Amplifier/Analog output section

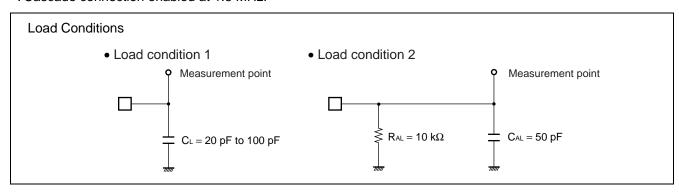
Damamatan	Comple of	D:	Conditions	Value			
Parameter	Symbol	Pin name	Conditions	Min.	Тур.	Max.	Unit
Power supply voltage	Vcca		_	2.7	3.0	3.6	V
Power supply current	ICCA	VCCA	#80 setting (Unloaded)	_	1.0	4.8	mA
Input leakage current	IILK2	D4 to D11	$V_{in} = 0$ to $V_{CC}A$	-10	_	+10	μΑ
"H" level digital input voltage	V <sub>IH2</sub>		_	0.5 × VccA	_	_	V
"L" level digital input voltage	V <sub>IL2</sub>		_	_	_	0.2 × VccA	V
"H" level digital output voltage	V <sub>OH2</sub>		Iон = -0.4 mA	VccA - 0.4	_	_	V
"L" level digital output voltage	V <sub>OL2</sub>		IoL = 2.5 mA	_	_	0.4	V
Analog output minimum voltage 1	V <sub>AOL1</sub>		I <sub>AL</sub> = 0 A #00 setting	GND	_	0.1	V
Analog output minimum voltage 2	V <sub>AOL2</sub>	AO1 to AO12	I <sub>AL</sub> = 0.5 mA #00 setting	-0.2	GND	0.2	V
Analog output minimum voltage 3	V <sub>AOL3</sub>	1AO1 10 AO12	I <sub>AH</sub> = 0.4 mA #00 setting	GND	_	0.15	V
Analog output minimum voltage 4	V <sub>AOL4</sub>		I <sub>AL</sub> = 1.0 mA #00 setting	-0.3	GND	0.3	V
Analog output maximum voltage 1	V <sub>АОН1</sub>		I <sub>AL</sub> = 0 A #FF setting	VccA - 0.1	_	VccA	V
Analog output maximum voltage 2	V <sub>AOH2</sub>	AO1 to AO12	I <sub>AL</sub> = 0.5 mA #FF setting	VccA - 0.2	_	VccA	V
Analog output maximum voltage 3	Vаонз	AU1 IU AU12	I <sub>AH</sub> = 0.4 mA #FF setting	VccA - 0.15	VccA	VccA + 0.15	V
Analog output maximum voltage 4	V <sub>A</sub> OH4		I <sub>AL</sub> = 1.0 mA #FF setting	VccA - 0.3	_	VccA	V

Note: IAH: Analog output sink current IAL: Analog output source current

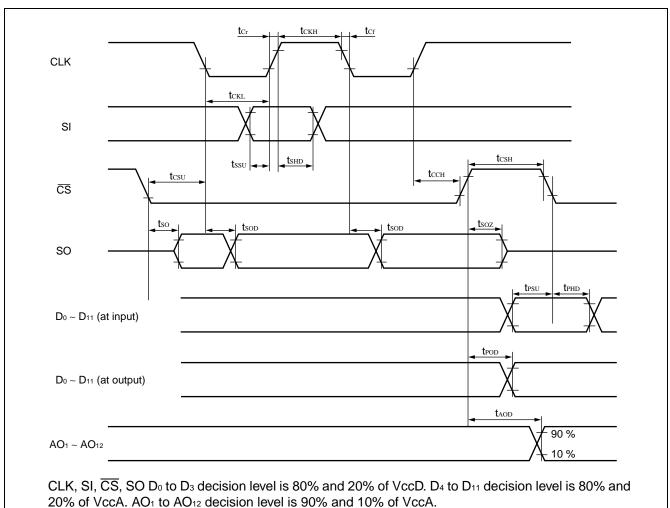
#### 2. AC Characteristics

Parameter	Symbol	Conditions	Value			l lm:4
			Min.	Тур.	Max.	Unit
Clock "L" level pulse width	<b>t</b> ckL	_	200	_	_	ns
Clock "H" level pulse width	<b>t</b> ckH	_	200			ns
Clock rise time	<b>t</b> cr	_	_	_	200	ns
Clock fall time	<b>t</b> Cf	_	_	_	200	ns
Serial input setup time	<b>t</b> ssu	_	30			ns
Serial input hold time	<b>t</b> shd	_	60	_	_	ns
Serial output delay time	tsod	See "Load condition 1"*	0	120	300	ns
CS input setup time	<b>t</b> csu	_	100			ns
CS hold time	<b>t</b> ccH	_	200	_	_	ns
CS "H" level hold time	<b>t</b> csH	_	100			ns
Data output enable time	<b>t</b> so	_	_		200	ns
Data output float time	<b>t</b> soz	_	_	_	200	ns
Parallel input setup time	<b>t</b> PSU	_	30			ns
Parallel input hold time	<b>t</b> PHD	_	60			ns
Parallel output delay time	<b>t</b> POD	See "Load condition 1"	_	120	300	ns
Analog output delay time	<b>t</b> aod	See "Load condition 2"	_	30	100	μs
Power supply rise time	<b>t</b> R	_	_	_	50	ms
Power-on reset non-startup power supply variation	$\Delta V_R$	—	-10	_	10	V/µs

#### \*: Cascade connection enabled at 1.5 MHz.

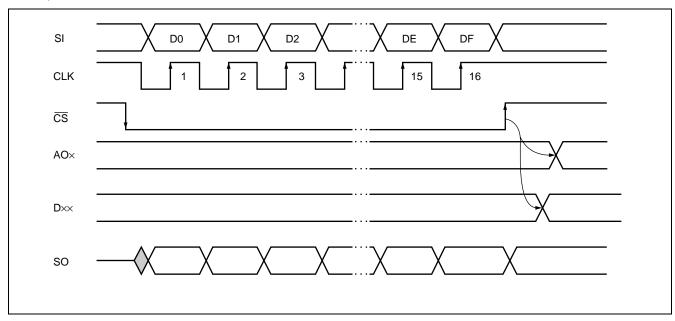


• Input/Output Timing (CS method)



#### ■ DATA INPUT/OUTPUT TIMING (Serial Bus Format)

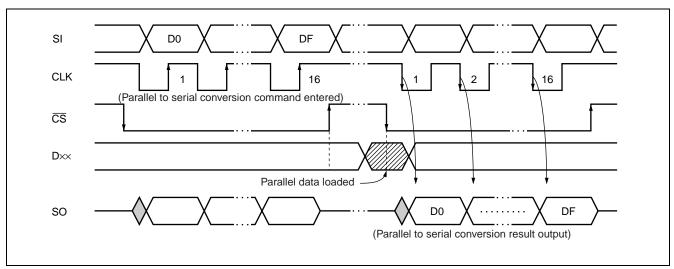
• Timing of D/A Converter Operation, I/O Expander Operation (serial to parallel conversion), and ESR Write Operation.



Data input is enabled at the fall of the  $\overline{\text{CS}}$  signal. 16-bit data is input, and executed by shift register command at the rise of  $\overline{\text{CS}}$ .

In D/A converter operation, analog output selected at the rise of  $\overline{CS}$  is converted. In serial to parallel conversion, digital output selected at the rise of  $\overline{CS}$  is converted. In ESR write operation, data is set in the ESR at the rise of [CS] and used to change pin states.

• I/O Expander Operation (parallel to serial conversion)



Data input is enabled at the fall of the  $\overline{CS}$  signal. 16-bit data (parallel to serial conversion command) is input, and commands received at the rise of  $\overline{CS}$ . At the fall of  $\overline{CS}$  the data from parallel input is loaded in the shift register from D4 to DF, and output from the SO pin timed to the fall of the CLK signal.

#### **■ USAGE PRECAUTIONS**

#### 1. Preventing Latch-Up

A condition known as "latch-up" may occur when the input or output pins of a CMOS IC device are exposed to voltages higher then  $V_{CC}D$  or  $V_{CC}A$  or lower than GND voltage, or when voltages are applied to the device in excess of rated values for  $V_{CC}D$ ,  $V_{CC}A$ , or  $V_{DD}$  to GND voltages. Latchup produces a rapid increase in power supply current, and may result in thermal destruction of elements. Users should take sufficient precautions to ensure that absolute maximum ratings are not exceeded at any time during use.

#### 2. Power Supply Pins

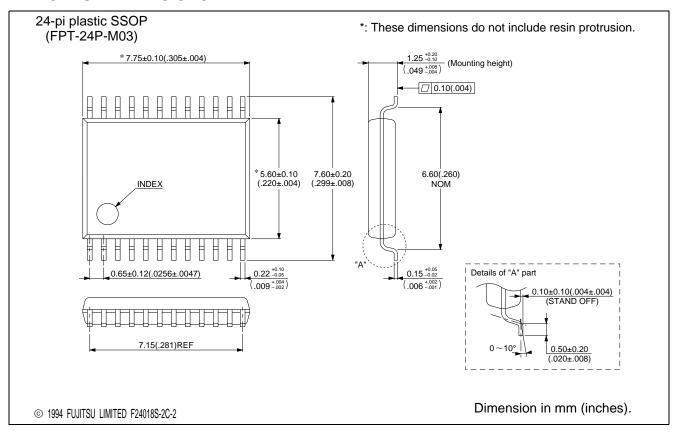
The power supply should be connected to the VccD, VccA, VDD, and GND terminals of the IC with as low an impedance as possible.

In addition, it is recommended that ceramic capacitors of approximately 0.1  $\mu$ F be connected as bypass capacitors between the VccD, VccA, and VpD terminals and the GND terminals.

#### **■ ORDERING INFORMATION**

Part number	Package	Remarks
MB40D001PFV	24-pin Plastic SSOP (FPT-24P-M03)	

#### **■ PACKAGE DIMENSIONS**



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