FUJITSU SEMICONDUCTOR
DATA SHEET

DS04-29101-3E

ASSP

BIDIRECTIONAL MOTOR DRIVER

MB3763

■ DESCRIPTION

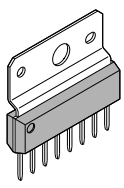
Fujitsu's MB3763 Motor Driver with forward/reverse control capability, is used in applications such as the front-loading mechanism in video tape, or the auto-reverse tape deck, driven by a TTL signal. The MB3763 has 300 mA drive units and braking capability with TTL control.

■ FEATURES

- Motor Drive Current : 300 mA maximum in a SIP Package
  : 150 mA maximum in a DIP/FTP Package
- Wide Power Supply Voltage Range: 4V to 18V
- TTL-control capability
- Standby capability when input is off.
- Brake capability at motor stop mode.
- Built-in diode for surge absorption
- Package: 8-pin plastic SIP package (Suffix: –PS)
  8-pin plastic DIP package (Suffix: –P)
  8-pin plastic FPT package (Suffix: –PF)

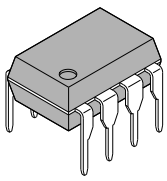
■ PACKAGE

Plastic SIP, 8 pin



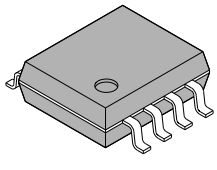
(SIP-08P-M01)

Plastic DIP, 8 pin



(DIP-08P-M01)

Plastic FPT, 8 pin



(FPT-08P-M01)

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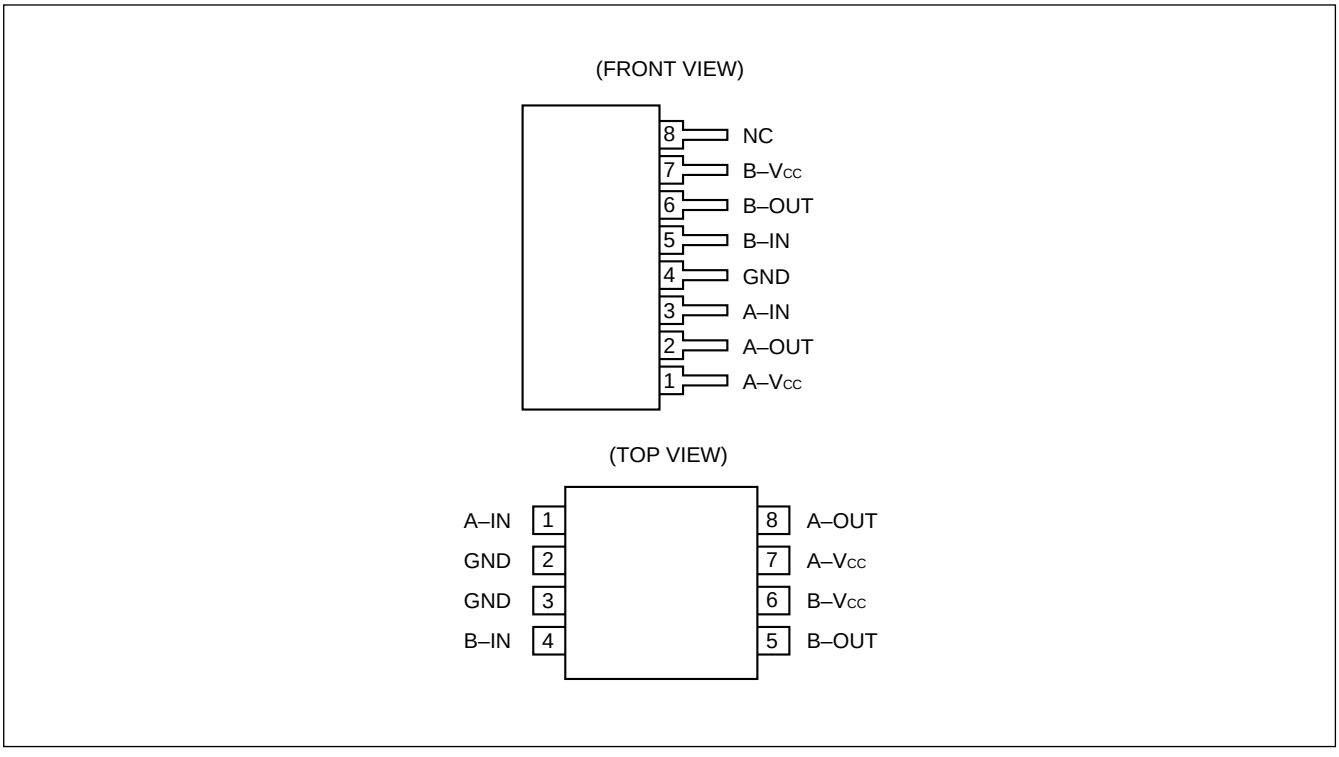
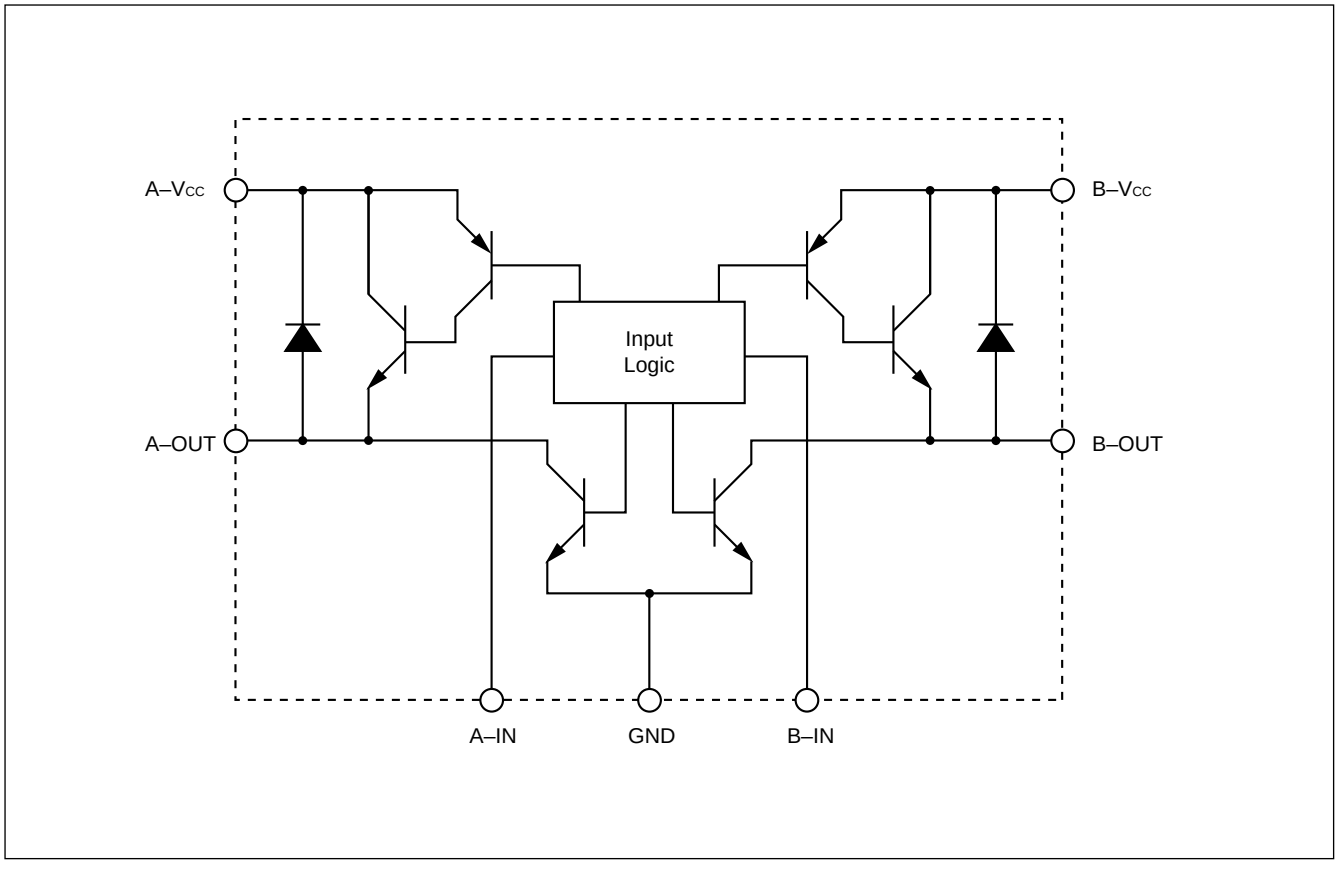
■ PIN ASSIGNMENT



■ BLOCK DIAGRAM



■ ABSOLUTE MAXIMUM RATINGS

(Ta = 25°C)

Parameter	Symbol	Value		Unit
		DIP/FPT (Plastic)	SIP (Plastic)	
Power supply voltage	V_{CC}	20	20	V
Output current	I_O	180 (330*1)	330	mA
Maximum output current	I_{OMAX}*3	1.2	1.2	A
Power Dissipation	P_D	560*2	1000	mW
Operating temperature	T_C	–20 to +75	–20 to +75	°C
Storage temperature	T_{STG}	–55 to +125	–55 to +125	°C

*1: $t_{ON} \leq 1$ sec, Duty = 50%
*2: Ta ≤ 60°C
*3: t ≤ 5 ms

Precautions: Permanent device damage may occur if the above Absolute Maximum Ratings are exceeded. Functional operation should be restricted to the conditions as detailed in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

■ RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Value		Unit
		DIP/FPT (Plastic)	SIP (Plastic)	
Power supply voltage	V_{CC}	4 to 18	4 to 18	V
Output current	I_O	0 to 150 (300*1)	0 to 300	mA
Input high voltage	V_{IH}*2	2.4 to V_{CC} + 0.3	2.4 to V_{CC} + 0.3	V
Input low voltage	V_{IL}	0 to 0.4	0 to 0.4	V

*1: $t_{ON} \leq 1$ sec, Duty = 50%
*2: When $V_{IH} \geq V_{CC}$, $I_{IH} \leq V_{CC} \times 0.2$ mA

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■ ELECTRICAL CHARACTERISTICS

(V_{CC} = 12V, I_O = 150/300 mA, Ta = 25°C)

Parameter	Symbol	Condition		Value			Unit
				Min.	Typ.	Max.	
Standby supply current	I_{CC0}	V_{CC} = 18V, V_{IA} = V_{IB} = 0V		—	—	1.0	mA
Power supply current	I_{CC1}	I_O = 0 mA		—	10	20	mA
	I_{CC2}	I_O = 150/ 300 mA	Plastic DIP/FPT	—	10	—	mA
			Plastic SIP	—	15	—	
	I_{CC3}	I_O = 0 mA, V_{IA} = V_{IB} = 2.4V		—	15	—	mA
Output high voltage	V_{OH}	Plastic DIP/FPT		11.0	11.2	—	V
		Plastic SIP		10.8	11.1	—	
Output low voltage	V_{OL}	Plastic DIP/FPT		—	0.1	0.2	V
		Plastic SIP		—	0.2	0.5	
Output saturation voltage	V_{SAT}	Plastic DIP/FPT		—	0.9	1.2	V
		Plastic SIP		—	1.1	1.7	
Input current	I_{IH}	V_{IN} = 2.4V		—	250	400	µA
Input switching prohibition time	T_{OFF}	—		10	—	—	µs

DIP: Dual line in package
SIP: Single in line package
FPT: Flat package

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■ FUNCTIONAL DESCRIPTIONS

FORWARD/REVERSE MODE (MODE B& C)

In this mode, the transistor pairs Q2-Q3 and Q1-Q4 work alternatively, changing the output current direction.

When the mode B is selected, Q2 and Q3 are active and Q1 and Q4 are inactive. Therefore A-OUT is at low level and B-OUT is at high level, with the current flowing from B-OUT to A-OUT through the motor. On the other hand, when the mode C is selected, the current flows in the reverse direction.

BRAKE/STOP MODE (MODE A)

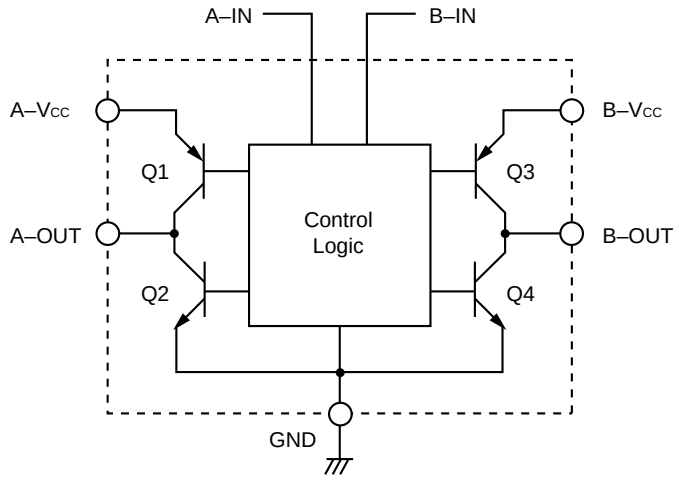
When the mode A is selected, Q1 and Q3 are inactive and Q2 and Q4 are active. A-OUT and B-OUT are stuck at low-level; terminals of motor are shorted and the motor is forced to stop.

STANDBY MODE (MODE D)

In this mode, all transistors are inactive and the current through the motor does not flow. When the power supply voltage is applied to A-V_{CC} and B-V_{CC}, the supply current is still less than or equal to 0.1 mA.

■ CONTROL MODE

Control Block Diagram



Mode	Input mode		Output mode		Operation
	A-IN	B-IN	A-OUT	B-OUT	
A	1	1	L	L	short (Brake)
B	1	0	L	H	Forward
C	0	1	H	L	Reverse
D	0	0	—	—	Open (Standby)

Notes: 1: ≥ 2.4V
0: ≤ 0.4V

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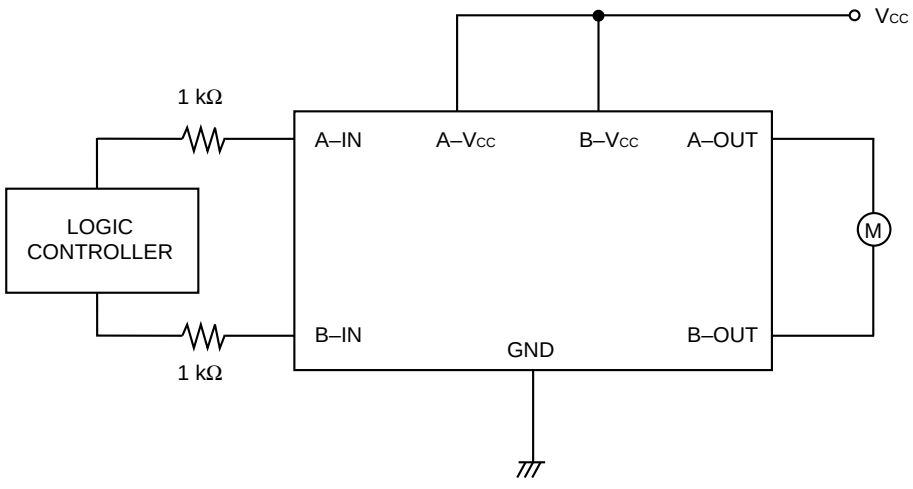
■ TYPICAL APPLICATION

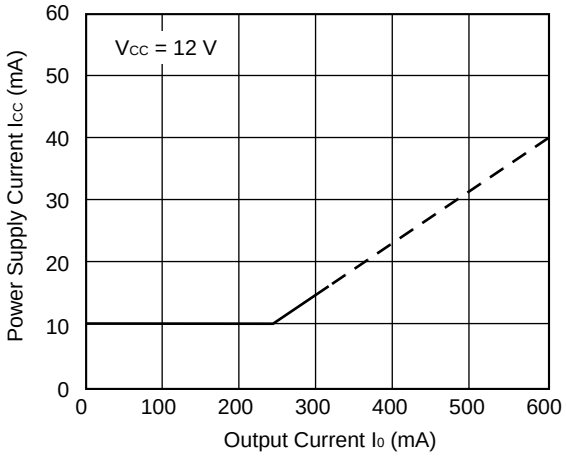
Typical Application Example



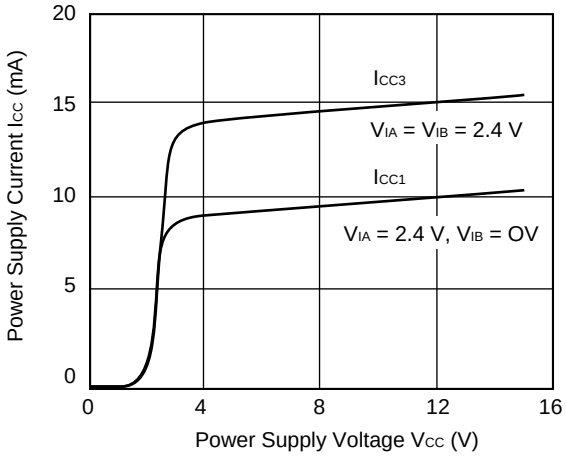
Note: In the case the control voltage is input when the power supply voltage is not applied because of the time lag between those two voltages, excess current flows into IC from the input terminals. In this case, please connect a resistor (≥ 1 kΩ) serially to input pin in order to prevent excess current flow.

■ TYPICAL PERFORMANCE CHARACTERISTICS

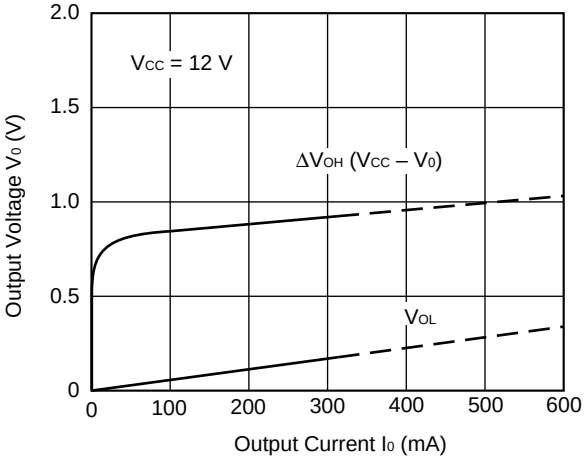
**Output Current vs.
Power Supply Current**



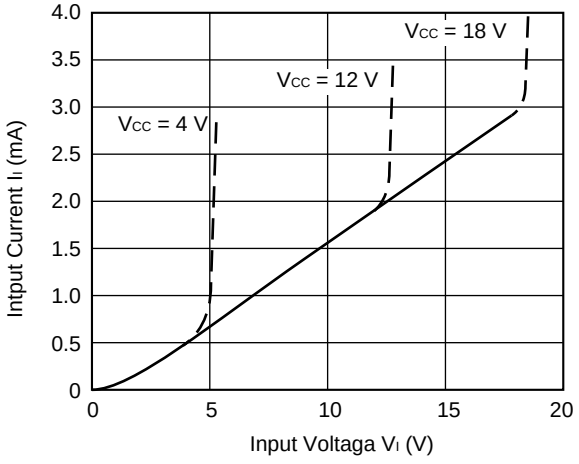
**Power Supply Voltage vs.
Power Supply Current**



**Output Current vs.
Output Voltage**



**Input Voltage vs.
Input Current**



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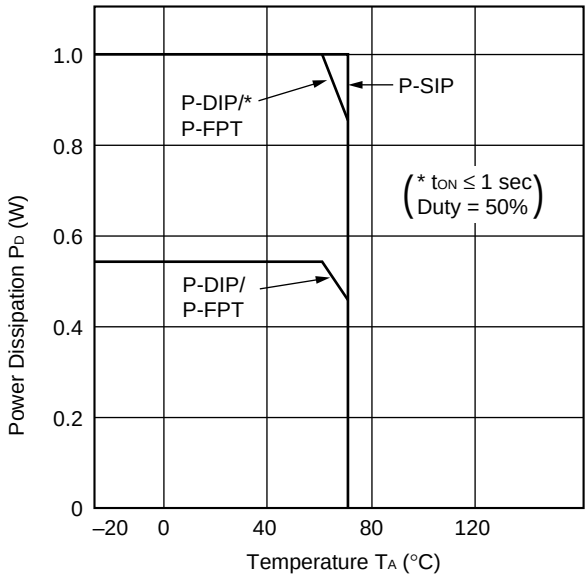
Temperature vs. Power Dissipation



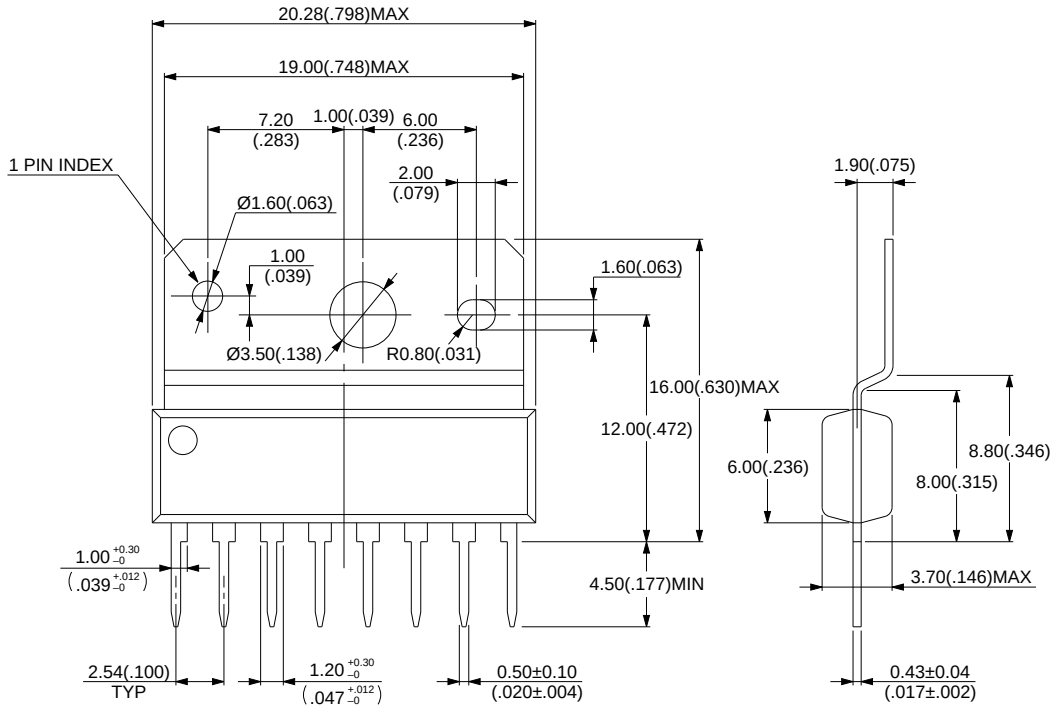
PF'S value is measured on the ceramic board (3.0 cm x 3.0 cm x 0.05 cm)

Notes P :Plastic DIP
PF :Plastic Flat Package
PS :Plastic SIP

Maximum power dissipation must be kept.

■ PACKAGE DIMENSIONS

8 pin, Plastic SIP
(SIP-08P-M01)



Dimensions in mm(inches)

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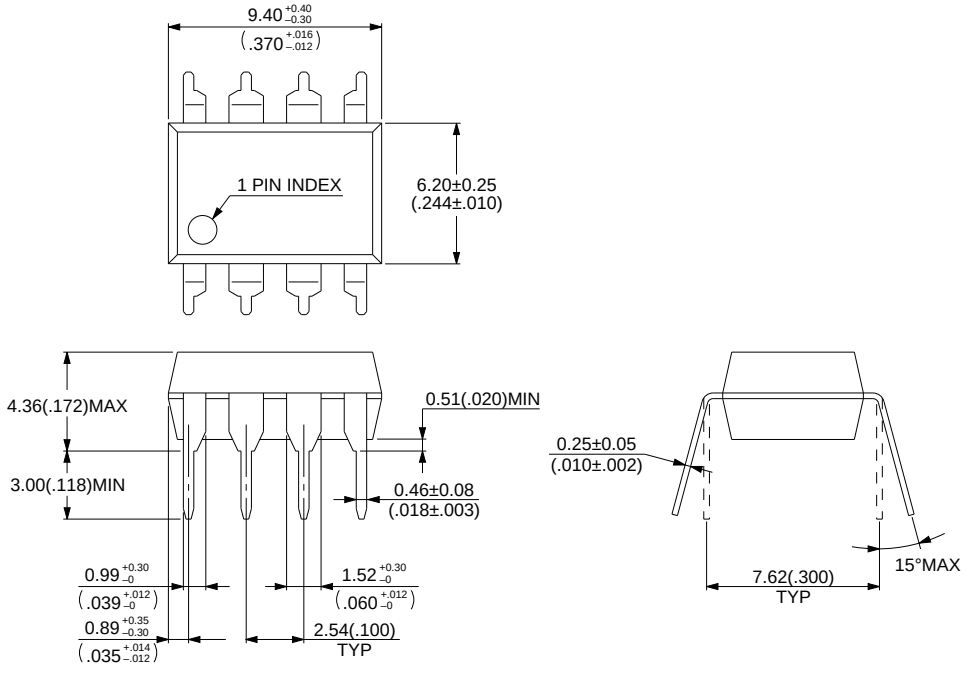
8 pin, Plastic DIP
(DIP-08P-M01)



Dimensions in mm(inches)

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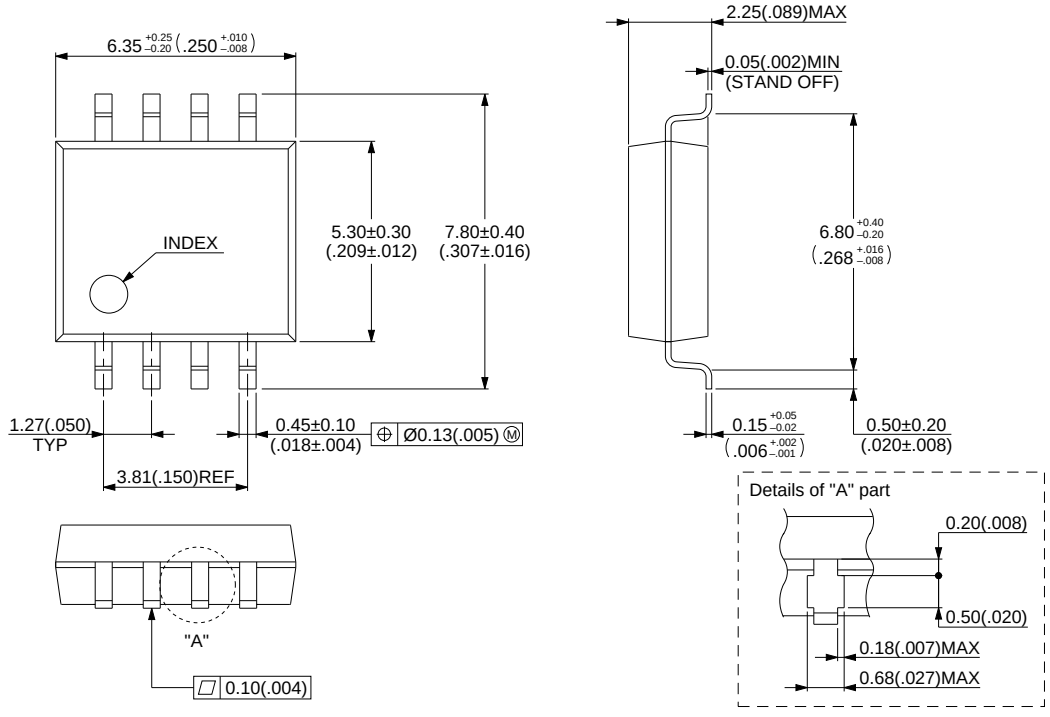
8 pin, Plastic SOP
(FPT-08P-M01)



Dimensions in mm(inches)

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